

Non-negative matrix factorization 101

A **standard NMF** [3] is represented as the following optimization problem:



Commonly optimized using **multiplicative update rules** (MURs):

$$\begin{split} \mathbf{W}^{(i+1)} &= \mathbf{W}^{(i)} \circ \frac{\mathbf{X}\mathbf{H}^T}{\mathbf{W}^{(i)}\mathbf{H}\mathbf{H}^T}, \\ \mathbf{H}^{(i+1)} &= \mathbf{H}^{(i)} \circ \frac{\mathbf{W}^T\mathbf{X}}{\mathbf{W}^T\mathbf{W}\mathbf{H}^{(i)}}, \end{split}$$

- ► Set of states $S = \{s_1, s_2, \dots, s_c\}$ + transition matrix $\{\mathbf{P}(S_i, S_j)\}_{i,j=1}^c = P(S_j|S_i)$
- ► Homogeneous (static) Markov chain: $\mathbf{x}_t = \mathbf{x}_0 \mathbf{P}^t$.
- ► Heterogeneous (dynamic) chain: $\mathbf{x}_t = \mathbf{x}_0 \prod_{i=1}^t \mathbf{P}_i$, with $\mathbf{x}_{i+1} = \mathbf{x}_i \mathbf{P}_i$.



Non-Negative Matrix Factorization Meets Time-Inhomogeneous Markov Chains

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✓ Surprising dependence of the **speed of convergence** of MUR on the product of **the second** largest singular values of S_i

- ► Test 1: synthetic example with unique factorization
- ► **Test 2**: mixture of Gaussian distributions



Figure 2. Results obtained with NNDSVD compared to random initialization: (left) reconstruction error and (middle left) product of second singular values of the transition matrices on the data admitting a unique factorization; (middle right) reconstruction error and (right) product of second singular values of the transition matrices on the mixture of 5 isotropic Gaussian distributions with n = 20000, k = 5 and $d \in \{10, \ldots, 100\}$.



Figure 3. Results obtained with Gillis' pre-processing presented in the same order as above with n = 200 for the case of the mixture of Gaussian distributions. For both cases, the variance (shaded area) around the mean curve over varying d is represented only for the case of the mixture of Gaussians as for the unique factorization all the parameters remain fixed. The code to reproduce the two figures is given in the Supplementary material.

- ✓ Forcing uniqueness with MUR requires solving an open algebraic problem

✓ Convergence speed depends on the second largest eigenvalues of the transition matrices: **confirmed in practice** for several methods and datasets

- [1] C. Boutsidis and E. Gallopoulos. Svd based initialization: A head start for nonnegative factorization. Pattern Recogn., 41(4):1350–1362, 2008.
- [2] Nicolas Gillis. Sparse and unique NMF through data preprocessir J. Mach. Learn. Res., 13(1):3349–3386, 2012



Experimental results

Baselines: random initialization, unique factorization with NNDSVD [1] and Gillis method [2]

✓ Theory is useful in practice to asses convergence speed based on the second largest singular values of transition matrices

Conclusion

✓ Explaining the lack of uniqueness in NMF with MUR trough equivalence to Markov chains

References

ve matrix	[3]	D. D. Lee and H. S. Seung. Learning the parts of objects by non-negative matrix factorization. <i>Nature</i> , 401:788–791, 1999.
ng.	[4]	Chih-Jen Lin. Projected gradient methods for NMF. <i>Neural Comput.</i> , 19(10):2756–2779, 2007.